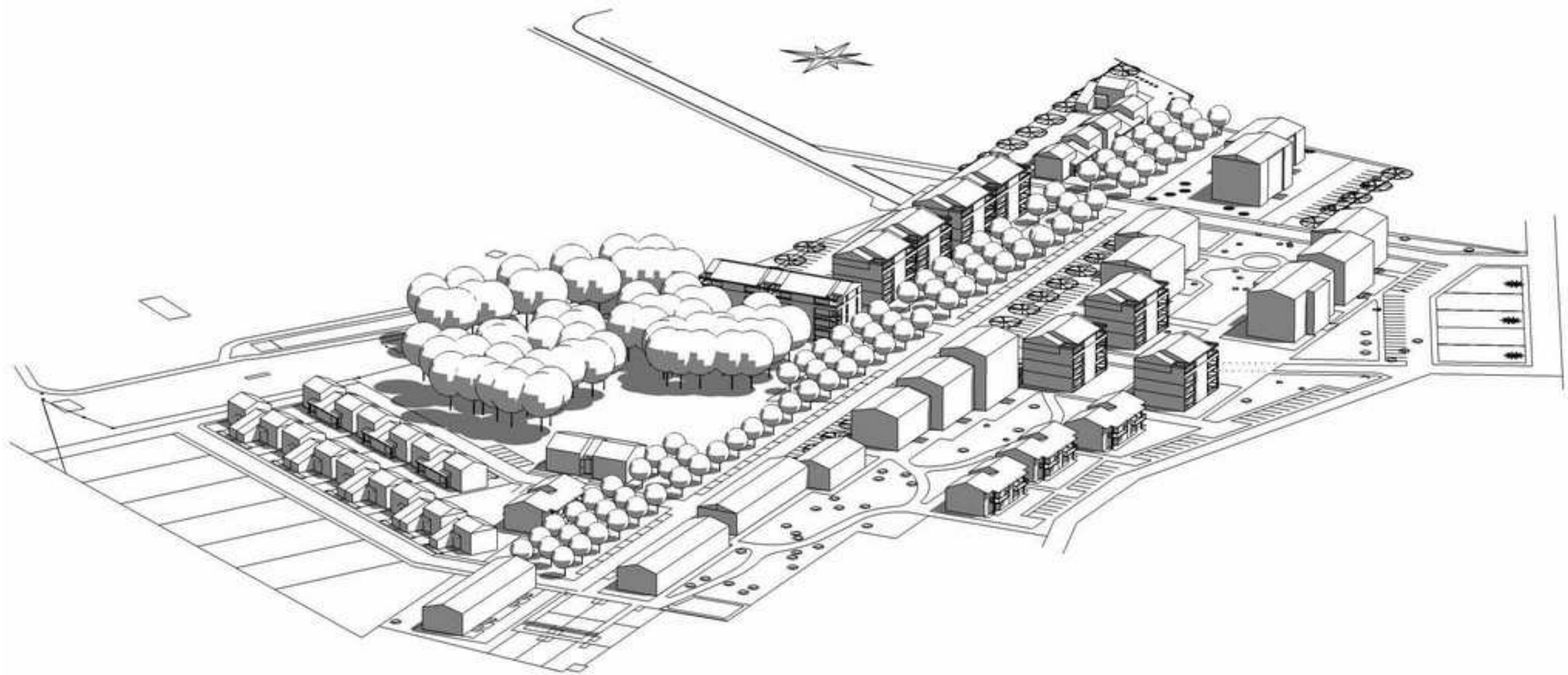


Plan de situation



Insertion



Plan-masse

